Prediction-Driven Knowledge Discovery from Data and Prior Knowledge

Gheorghe Tecuci¹, Dorin Marcu¹, Steven Mirsky², Alison Robertson³

¹Learning Agents Center, Department of Computer Science, School of Computing, George Mason University, Fairfax, VA 22030, USA ²Sustainable Agricultural Systems Lab, USDA, ARS, BARC-West, 10300 Baltimore Avenue, Beltsville, MD 20705, USA ³Department of Plant Pathology and Microbiology, Iowa State University, 2213 Pammel Drive, Ames, IA 50011, USA tecuci@gmu.edu; dmarcu@gmu.edu; steven.mirsky@usda.gov; alisonr@iastate.edu

Abstract

This paper presents a novel approach to knowledge discovery. As opposed to the vast majority of existing approaches that use statistical machine learning to discover knowledge from data, we synergistically integrate ideas from artificial intelligence, machine learning, science of evidence, logic and probabilities to use both existing incomplete domain knowledge and imperfect data to discover new knowledge. We illustrate this approach in the precision agriculture domain considering the practices associated with cover crops, and learning how abiotic and biotic factors and cover crops management practices (planting and termination dates and methods) influence cereal cover crop biomass accumulation across corn-growing, soybean-growing, and cotton-growing regions of the U.S.

Introduction

Knowledge discovery from data (KDD) is a very active area of research that is concerned with the development and application of methods, such as classification, clustering, and association rule mining, to discover useful and interesting information from large collections of data (Tan et al., 2019).

We present research on the development of a novel approach that enables the discovery of new knowledge from existing data and prior knowledge, by synergistically integrating the scientific method of hypothesis generation and testing (Tecuci et al., 2016a), evidence-based reasoning (Schum et al., 2009; Tecuci et al., 2016b), multistrategy machine learning (Boicu et al., 2001; Tecuci, 1988; 1998),

instructable agents (Tecuci and Hieb, 1996; Tecuci et al., 2000; 2002; 2005; 2007b; 2008; Huang et al., 2020), automated search, and mixed-initiative interaction (Tecuci et al., 2007a).

Section 2 presents the addressed discovery problem and method. Section 3 presents the domain used to illustrate them. Section 4 presents the method in detail. Finally Section 5 presents the current status and future work.

Knowledge Discovery Problem and Method

Given

- *Incomplete knowledge* about a domain (e.g., Biomass Accumulation of Cover Crops).
- *Imperfect data* on specific combinations of values of domain variables, data that may be incomplete, inconclusive, ambiguous, dissonant, and/or with various degrees of accuracy. For example, data obtained from field trials and previously collected farm data.

Discover *New knowledge* relevant to biomass accumulation of cover crops.

Method (summarized in Figure 1). We want to improve our partial understanding of how some domain variables influence other domain variables. We start by selecting a *reference case* for which actual data about these variables exist. We then use our current knowledge to develop a *predictive model* in the form of a *probabilistic inference network* that explains how the values of some variables from the reference case determine the values of other variables. Next, we iteratively and automatically apply the predictive model to other cases for which individual data exist, to identify cases where the predicted results differed from the actual results. *Explanation of the differences between the reference case and these cases leads to the discovery of new knowledge and the iterative improvement of the predictive model.*

We claim, but still need to experimentally prove, that the proposed approach has several advantages over the existing



KDD approaches:

- Unlike the existing KDD approaches that rely on large amounts of data to draw conclusions, our approach can work with a few studies to formulate hypotheses that could explain the observed phenomenon and then test these hypotheses on the remaining studies. But this approach enables us to efficiently work with massive amounts of data as well.
- The individual study data do not need to be complete or uniform because they are treated as evidence on the considered hypotheses, evidence that can be incomplete, inconclusive, ambiguous, dissonant, or have various degrees of accuracy.
- We do not need to perform new experiments (that may be expensive and may require significant time and effort) because the formulated hypotheses can be tested on existing data.

Biomass Accumulation of Cover Crops

Cover crops (CC) are non-marketed crops that are planted between periods of cash crop production to provide a diverse array of ecosystem services including increased water and nutrient retention and availability, pest management, and greater soil health. As a result, CCs could also increase crop yield stability and resilience in a changing climate (Villamil et al., 2006; Kaspar et al., 2001; Meisinger et al., 1991; Ruffo et al., 2004; Shipley et al., 1992). Figure 2 summarizes our current partial knowledge on the main factors influencing CC biomass (Thapa et al., 2018). To reap various ecosystem services (reduced soil erosion, improved nutrient cycling, etc.), substantial CC biomass production is required. Extrinsic and intrinsic factors affect biomass production. We need to discover knowledge of how abiotic and biotic factors, and management practices (planting and termination dates, and methods) influence biomass accumulation across corn-, soybean-, and cotton- growing U.S. regions.

We start by selecting a reference farm case for which actual data exists. We then use our current knowledge on CC management to develop a predictive model in the form of a *Wigmorean argumentation* (Wigmore, 1913; 1937; Schum, 1987; 2001; Tecuci et al., 2016a) that explains how various



Figure 2. Cover crop knowledge.

intrinsic and extrinsic factors from the reference case support the production of high biomass. Next, we iteratively and automatically apply the predictive model to other farm cases for which individual data exist, to identify cases where the predicted results differed from the actual results. *Explanation of the differences between the reference case* and these farm cases leads to the discovery of new knowledge and the iterative improvement of the predictive model.

Illustration of the Discovery Method

Step 1: Selection of a Reference Farm Case Fref

As shown in Figure 3, the first step of the investigation and discovery process is to select a reference farm case F_{ref} that will guide the discovery of knowledge applicable to the class of cases similar to it. In this illustration, F_{ref} is *Maryland Farm1 during the 2018-2019 cover crop season*, a past case in which the cover crops produced high biomass.

Step 2: Argumentation that Explains the Phenomenon on F_{ref}

In this step the current cover crops knowledge is used to develop a predictive model (in the form of a Wigmorean argumentation) that explains how the various intrinsic and extrinsic factors supported the production of high CC biomass in case F_{ref} .

Wigmorean Argumentation for Evidence-based Hypothesis Assessment

Figure 4 shows an abstract example of a Wigmorean argumentation structure used to assess a hypothesis based on evidence.

The hypothesis H to be assessed is decomposed into simpler hypotheses by considering both favoring arguments (supporting the truthfulness of H), under the left (green) square, and disfavoring arguments (supporting the falsehood of H), under the right (pink) square. Each argument is an independent strategy of showing that H is true or false, and is characterized by a specific relevance or strength. The argument consists either of a single subhypothesis (e.g., H_3) or a conjunction of sub-hypotheses (e.g., $H_1 \& H_2$). The sub-hypotheses from these arguments are further decomposed through other arguments, leading to simpler and simpler (sub-sub-)hypotheses that can be more accurately assessed based on evidence. Evidence is any observable sign, datum, or item of information that is relevant in deciding whether a statement or hypothesis (e.g., a scientific claim) is true or false (Schum, 2001).

Consider, for example, sub-sub-hypothesis H_{2b} . There are two items of evidence relevant to this hypothesis, the favoring evidence item E_1 , and the disfavoring evidence item E_2 . Each item of evidence has three credentials that need to be assessed: accuracy, relevance, and inferential



Figure 3. The envisioned approach to knowledge discovery from data.

force. The *accuracy* of evidence answers the question: "What is the probability that the evidence is true?" The *relevance* of evidence to a hypothesis answers the question: "What would the probability of the hypothesis be if the evidence were true?" These two credentials are used to compute the *inferential force or weight* of the evidence on the hypothesis, which answers the question: "What is the probability of the hypothesis, based only on this evidence?" This is computed as the minimum between the accuracy and relevance. For example, the inferential force of E_1 is almost certain, that of E_2 is barely likely.

The probability of sub-sub-hypothesis H_{2b} is determined by balancing the inferential force of the favoring evidence with that of the disfavoring evidence. Once the probabilities of the bottom-level hypotheses have been computed based on evidence, the probabilities of the upper level hypotheses are computed based on the logical structure of the Wigmorean argumentation (conjunctions and disjunctions of hypotheses), using min-max probability combination rules common to the Fuzzy probability view (Zadeh, 1983;



Negoita and Ralescu, 1975; Schum 2001) and the Baconian probability view (Cohen, 1977; 1989; Schum, 2001). These rules are much simpler than the Bayes rule used in the Bayesian probability view (Schum, 2001), or the Dempster-Shafer rule in the Belief Functions probability view (Shafer, 1976).

Such Wigmorean argumentations are easy to develop and understand, and can be learned by an intelligent software agent, such as the proposed KDA.

Thus, the specific Wigmorean argumentation for our example of biomass production of cover crops (Figure 5) shows how the factors in Figure 2 (e.g., climate, soil) supported the production of high biomass (top hypothesis) in the case of Maryland Farm1 during the 2018-2019 cover crop season (F_{ref}). There are two arguments favoring the top hypothesis. The left argument, based on the current cover crop knowledge, consists of three sub-hypotheses and states that favorable environmental, management, and genetic factors led to high biomass. Each of these factors has its own argument. For example, favorable environmental conditions were determined by favorable soil and climate conditions. Favorable soil conditions, in turn, were determined by high residual Nitrogen and excess drainage. These lower level conditions are supported by actual evidence (that is, data from the case study), E1: Maryland Farm1 2018-19 has high residual N and E2: Maryland Farm1 2018-19 has excess drainage. Now, following the inference steps from bottomup, from these evidence items to the top hypothesis, one concludes high biomass on Maryland Farm1. The right argument of the top hypothesis is the direct evidence from the case data, that the biomass produced was high, E7: Maryland Farm1 2018-19 has high biomass.

Thus, in this example, the argument based on knowledge correctly predicted the actual biomass produced. The question is: *How can we determine whether this is true for all the recorded cases?* That is, how can we determine whether, in all the recorded cases, the result predicted using the current cover crop knowledge is consistent with what was actually produced? Any discovered inconsistency is an indication of an imperfect Wigmorean prediction model and thus of imperfect knowledge. We will now discuss how these inconsistencies can be used to correct or extend this knowledge.

Step 3: Knowledge-Based Generalization of the Argumentation

Ontology Development. Based on the argumentation from Figure 5 we develop the ontology (bottom right-hand Figure 5) to represent the entities from the argumentation, as well as similar ones. The ontology contains concepts from the

application domain, such as farm, plot, plant and soil characteristic, which define the hierarchical types (taxonomies) for the entities in the argumentation. For example, Maryland Farm1 is a Maryland farm, which is a farm, while Plot1 is a plot. The ontology also represents the relationships between entities, for example, that Plot1 has high residual Nitrogen and excessive soil drainage.

Teaching the Discovery Assistant. We need to teach the KDA to automatically develop argumentations like the one from Figure 5 based on farm data from other cases. As illustrated in Figure 6, the KDA learns a general hypothesis analysis rule from each specific argument that decomposes a hypothesis into sub-hypotheses. For example, from the top-left argument in Figure 6 the assistant learns the

Figure 5. Wigmorean argumentation (left) and corresponding ontology fragment (bottom right).

hypothesis analysis rule A1 shown at the bottom right of that figure.

The learned rule consists of the argument pattern obtained by replacing the entities from the top-left argument in Figure 6 (cereal rye P1, October 2018, Maryland Farm1, April 2019, ...) with corresponding variables (i.e., ?O1, ?O2, etc.). The rule also has an applicability condition that indicates the possible values of these variables for which the reasoning pattern is likely to be correct, based on the hierarchy of concepts from the ontology in Figure 5. Notice however that, instead of a single applicability condition, the KDA learns a lower bound and an upper bound for this condition, using two complementary learning strategies:

The lower bound of the condition is generated by employing the strategy of a *cautious learner* that wants to minimize the chances of making mistakes when employing the learned pattern. This strategy increases the confidence of the KDA in the correctness of its reasoning. However, the KDA may fail to apply the reasoning pattern in situations where, in fact, it is applicable. The upper bound of the condition is generated by employing the strategy of an *aggressive learner* that wants to maximize the opportunities of employing the learned pattern. This strategy increases the number of situations where the rule can be applied, although in some of these situations the reasoning may not be correct.

The two bounds may be refined, and may even become identical, based on additional example arguments encountered by the KDA.

The KDA also learns an evidence collection rule for each argument that reduces a hypothesis to an evidence item. A specialized collection agent can then search the data repository of recorded cases for the evidence item. The design and management of specialized collection agents are critical for the automatic extraction of evidence from existing farm data.

The vast majority of the current machine learning approaches rely heavily on statistics and learn single functions from a large number of examples. Such

Figure 6. Rules learned from the argumentation in Figure 5.

approaches are not applicable for our learning problem because sets of examples to learn from (i.e., arguments) do not exist and would require a significant effort to create. Instead, an agricultural scientist explains to the KDA the individual arguments from Figure 5 by selecting the corresponding relations from the ontology or by defining them, and the agent learns rules as ontology-based generalizations of these arguments, as discussed above (Figure 6). The explanations provided by the agricultural scientist to the KDA point directly to the relevant features of the individual arguments, enabling rapid learning. Thus, these features do not need to be discovered through the statistical comparison of a large number of positive and negative argument examples (that are often not available), as current (statistics-based) inductive learning methods do (Witten et al. 2011; Flach, 2012; Alpaydyn, 2020).

Step 4: Discovery of Favoring and Disfavoring Cases

This step involves a process of knowledge-based search and

Figure 7. Automatically generated argumentation that is inconsistent with the evidence.

classification. The generalized argumentation is automatically applied to cases that are similar to the reference case F_{ref} . The cases are split into *favoring* cases (high biomass) and *disfavoring* cases (low or medium biomass).

Step 5: Selection of Most Similar Disfavoring Case

Since there are disfavoring cases, the argumentation from Figure 6 is incomplete and/or partially incorrect. We thus have to discover what factors were not taken into account, and improve this argumentation. To facilitate this complex knowledge discovery process, the KDA selects a new case F_s from the set of disfavoring ones that is *most similar* to the reference farm case F_{ref} (i.e., Maryland Farm1). Since there will be very fewer factors that are different, some may be responsible for the difference in cover crop biomass. This farm case F_s might be, for example, *Virginia Farm3 during the 2017-2018 cover crop season*. The corresponding instantiation of the generalized argumentation from Figure 6 is shown in Figure 7. Notice that, in this case, the direct evidence E37 disfavors the top hypothesis because the actual cover crop biomass produced was medium.

Step 6: Hypothesis-Driven Explanation Discovery

Now the agricultural scientist has to hypothesize an explanation for the difference in cover crop biomass between the two *very similar cases* F_{ref} (Maryland Farm1) and F_s (Virginia Farm3). After comparing data from these two farms, the agricultural scientist hypothesizes that the cause of medium biomass at Virginia Farm3 is the soil pH during the 2017-2018 season, which is too low. Since the soil pH at the Maryland Farm1 during the 2018-2019 season was neutral, the agricultural scientist hypothesizes that an additional relevant soil condition for high biomass (besides high residual Nitrogen and excessive drainage shown in Figure 5) is neutral pH.

Step 7: Explanation-Based Refinement of the Argumentation

As a result, the argumentation from Figure 5 inferring high biomass for the reference case F_{ref} is extended (Figure 8) with the additional soil pH condition generalized as discussed in Step 3, validated on Virginia Farm3 during the 2017-2018 season, and automatically applied to all similar cases in Step 4. If the total number of favoring cases is not increased (or, equivalently, the total number of disfavoring cases not decreased), the hypothesis formulated in Step 6 is rejected and a new explanation has to be hypothesized. If, however, the total number of favoring cases is increased, the hypothesis is accepted and represents new discovered knowledge.

Loop 5-6-7-3-4: Learning Argumentation-Based Explanation Models

The 5-6-7-3-4 loop (Figure 3) is repeated, leading to new

Figure 8. Refined argument.

discovered knowledge, until all cases similar to F_{ref} are correctly predicted, with the possible exception of a few anomalous cases. The result of this process is the discovery of new knowledge and a generalized argumentation that correctly infers and explains cover crop biomass for the class of cases similar to F_{ref} .

Then, the process restarts with Step 1, in which a new reference farm case is selected from the remaining data (if any). The entire process is repeated along the steps from Figure 3 as discussed so far, until all available farm cases are correctly predicted, with the possible exception of a few anomalous cases (including those for which the data may be incorrect or incomplete).

Current Status and Future Research

We are currently developing an intelligent system, called the Knowledge Discovery Assistant (KDA) that implements the presented approach. Many of the modules of the KDA are customizations of modules of Cogent, a cognitive assistant for intelligence analysis (Tecuci et al., 2018) and of Disciple-EBR, a tool set for developing agents for evidence-based reasoning tasks (Tecuci et al. 2016b).

Once the prototype of the KDA is developed, it will be used by agricultural scientists to discover knowledge in three areas, one being the biomass accumulation of CC discussed above. The other two are briefly presented below.

Role of Cover Crops in Weed Suppression. The role of CCs in weed suppression is complex and dependent on many factors, including geographical region, climate, and soil. Past research has shown that CC mulch levels are highly correlated with suppression of summer annual weeds. However, this relationship varies considerably with climate and soil type and other plant-soil interactions. To date, there has not been an integration of these factors to elucidate how

climate, soil, and management intersect to drive weed suppression. Our incomplete understanding of the factors influencing weed growth stymies our ability to parameterize models that capture the complexity of cover crop-weed interactions. We plan to apply the KDA to improve our current understanding of how climate, soil, and weed seedbank size interact with CC biomass to drive weed suppression.

Foliar Fungicide Applications to Field Crops. In the past two decades, fungicide use on field crops has increased considerably (Mueller et al., 2021). Several factors have been suggested for this growth in fungicide use including increased commodity prices, more fungicide products registered for use on field crops, greater disease prevalence, and marketing (Wise and Mueller, 2011). Fungicides have traditionally been applied to reduce disease, however, in more recent years they have been applied for their physiological plant effects that may contribute to yield increases. Research in soybean and other crops, however, indicates these physiological effects are inconsistent, or do not always result in a measurable yield increase (Bertelsen et al., 2001; Khan and Carlson, 2009; Robertson et al., 2020). We need to understand the abiotic and biotic, management, and environmental factors that contribute to greater yields in field crops to identify situations where an application of a fungicide could result in greater yields and a return on investment.

The KDA will be freely available to scientists of any ilk and we will support its use.

Acknowledgements

David Schum (1932 – 2018) has significantly influenced our work on evidence-based reasoning. Mihai Boicu contributed to our research on knowledge representation, reasoning and learning, and the development of cognitive agents. Victoria Akroyd provided useful comments on this research.

References

Alpaydyn, A. 2020. *Introduction to Machine Learning*. MIT Press. Bertelsen, F.R.; de Neergaard, E.; and Smedegaard-Petersen, V. 2001. Fungicidal effects of azoxystrobin and epoxiconzole on phyllosphere fungi, senescence and yield of winter wheat. *Plant Pathology*, 50 (2): 190-205.

Boicu, M.; Tecuci, G.; Stanescu, B.; Marcu, D.; and Cascaval, C.E. 2001. Automatic Knowledge Acquisition from Subject Matter Experts. In *Proc. of the 13th Int. Conf. on Tools with Artificial Intelligence (ICTAI)*, November 7-9, Dallas, TX: 69-78.

Cohen, L.J. 1977. *The Probable and the Provable*. Oxford: Clarendon Press.

Cohen, L.J. 1989. An Introduction to the Philosophy of Induction and Probability. Oxford: Clarendon Press.

Flach, P. 2012. Machine Learning: The Art and Science of Algorithms that Make Sense of Data. Cambridge University Press.

Kaspar, T.; Radke, J.; and Laflen, J. 2001. Small grain cover crops and wheel traffic effects on infiltration, runoff, and erosion. Journal of Soil and Water Conservation, 56: 160-164.

Khan, M.F.R., and Carlson, A.L. 2009. Effect of fungicides on sugar beet yield, quality, and postharvest respiration rates in the absence of disease. *Plant Health Progress*.

Huang, J.; An, Z.; Meckl, S.; Tecuci, G.; and Marcu, D. 2020. Complementary Approaches to Instructable Agents for Advanced Persistent Threats Detection. *Studies in Informatics and Control*, 29 (3).

Meisinger, J.J.; Hargrove, W.L.; Mikkelsen, R.L.; Williams, J.R.; and Benson, V.W. 1991. Effects of cover crops on groundwater quality. In W.L. Hargrove, (editor), *Cover crops for clean water*, Soil and Water Conservation Society, Ankeny, IA: 57-84.

Mueller, D.S.; Wise, K.; Bradley, C.; Sisson, A.; Smith, D.; Hodgson, E.; Tenuta, A.; Friskop, A.; Conley, S.; Faske, T.; Sikora, E.; Giesler, L.; and Chilvers, M. 2021. Fungicide Use in Field Crops. *CPN* 4008. doi.org/10.31274/cpn-20210329-0.

Negoita, C.V., and Ralescu, D.A. 1975. Applications of Fuzzy Sets to Systems Analysis. New York, NY: Wiley.

Robertson, A.E.; Serrano, M.; Acharya, J.; Shriver, J.; Beckman, J.; Huffman, C.; Pecinovsky, K., Rees, M., Schaben, D.; Schnabel, M.; Sievers, J.; and Tuttle, T. 2020. The effect of foliar fungicides applied at tasseling on stalk lodging in corn. *Plant Heath Progress*, 21: 2-8. doi.org/10.1094/PHP-08-19-0049-RS.

Ruffo, M.L.; Bullock, D.G.; and Bollero, G.A. 2004. Soybean yield as affected by biomass and nitrogen uptake of cereal rye in winter cover crop rotations. *Agronomy Journal*, 96: 800-805.

Schum, D. 1987. Evidence and Inference for the Intelligence Analyst. Lanham, MD: University Press of America.

Schum, D.A. 2001. *The Evidential Foundations of Probabilistic Reasoning*. Northwestern University Press.

Schum, D.; Tecuci, G.; and Boicu, M. 2009. Analyzing Evidence and Its Chain of Custody: A Mixed-Initiative Computational Approach. *International Journal of Intelligence and CounterIntelligence*, 22 (2): 298-319.

Shafer, G. 1976. *A Mathematical Theory of Evidence*. Princeton, NJ: Princeton University Press.

Shipley, P.R.; Meisinger, J.J.; and Decker, A.M. 1992. Conserving residual corn fertilizer nitrogen with winter cover crops. *Agronomy Journal*, 84: 869–876.

Tan, P.-N.; Steinbach, M.; Karpatne, A.; and Kumar, V. 2019. *Introduction to Data Mining (Second Edition)*. Pearson.

Tecuci, G. 1988. DISCIPLE: A Theory, Methodology and System for Learning Expert Knowledge. *These de Docteur en Science* (in English), 197 pages, University of Paris-South, France.

Tecuci, G. 1998. Building Intelligent Agents: An Apprenticeship Multistrategy Learning Theory, Methodology, Tool and Case Studies. San Diego, CA: Academic Press.

Tecuci, G., and Hieb, M.H. 1996. Teaching Intelligent Agents: The Disciple Approach. *International Journal of Human-Computer Interaction*, 8 (3): 259-285.

Tecuci, G.; Boicu, M.; Bowman, M.; Marcu, D.; Shyr, P.; and Cascaval, C. 2000. An Experiment in Agent Teaching by Subject Matter Experts. *International Journal of Human-Computer Studies*, 53: 583-610.

Tecuci, G.; Boicu, M.; Marcu, D.; Stanescu, B.; Boicu, C.; Comello, J.; Lopez, A.; Donlon, J.; and Cleckner, W. 2002. Development and Deployment of a Disciple Agent for Center of Gravity Analysis. In *Proc. of the 18th National Conf. of Artificial Intelligence and the 14th Conference on Innovative Applications* of Artificial Intelligence, Edmonton, Alberta, Canada: 853-860.

Tecuci, G.; Boicu, M.; Boicu, C.; Marcu, D.; Stanescu, B.; and Barbulescu, M. 2005. The Disciple-RKF Learning and Reasoning Agent. *Computational Intelligence*, 21: 462-479.

Tecuci, G.; Boicu, M.; and Cox, M.T. 2007a. Seven Aspects of Mixed-Initiative Reasoning: An Introduction to the Special Issue on Mixed-Initiative Assistants, *AI Magazine*, 28 (2): 11-18.

Tecuci, G.; Boicu, M.; Marcu, D.; Boicu, C.; Barbulescu, M.; Ayers, C.; and Cammons, D. 2007b. Cognitive Assistants for Analysts. *Journal of Intelligence Community Research and Development (JICRD)*. Also in Auger, J., and Wimbish, W. (editors), *Proteus Futures Digest: A Compilation of Selected Works Derived from the 2006 Proteus Workshop*, 303-329.

Tecuci, G.; Boicu, M.; Marcu, D.; Boicu, C.; and Barbulescu, M. 2008. Disciple-LTA: Learning, Tutoring and Analytic Assistance. *Journal of Intelligence Community Research and Development*.

Tecuci, G.; Marcu, D.; Boicu, M.; Schum, D.A.; and Russell, K. 2011. Computational Theory and Cognitive Assistant for Intelligence Analysis. In *Proceedings of the 6th International Conference on Semantic Technologies for Intelligence, Defense, and Security - STIDS 2011*, November 16-18, Fairfax, VA: 68-75.

Tecuci, G.; Marcu, D.; Boicu, M.; and Schum, D.A. 2015. Cogent: Cognitive Agent for Cogent Analysis. In *Proceedings of the 2015 AAAI Fall Symposium "Cognitive Assistance in Government and Public Sector Applications,*" Arlington, VA. Technical Report FS-15-02: 58-65, Palo Alto, CA: AAAI Press.

Tecuci, G.; Schum, D.A.; Marcu, D.; and Boicu, M. 2016a. Intelligence Analysis as Discovery of Evidence, Hypotheses, and Arguments: Connecting the Dots. Cambridge University Press.

Tecuci, G.; Marcu, D.; Boicu, M.; and Schum, D.A. 2016b. *Knowledge Engineering: Building Personal Learning Assistants for Evidence-based Reasoning*. Cambridge University Press.

Tecuci, G.; Kaiser, L.; Marcu, D.; Uttamsingh, C.; and Boicu, M. 2018. Evidence-based Reasoning in Intelligence Analysis: Structured Methodology and System. *Computing in Science and Engineering*, 20 (6): 9-21.

Tecuci, G.; Meckl, S.; Marcu, D.; and Boicu, M. 2019. Instructable Cognitive Agents for Autonomous Evidence-Based Reasoning. *Advances in Cognitive Systems*, 8.

Thapa, R.; Poffenbarger, P.; Tully, K.; Ackroyd, V.; Kramer, M.; and Mirsky, S.B. 2018. Biomass production and nitrogen accumulation by hairy vetch/cereal rye mixtures: A meta-analysis. *Agronomy Journal*, 4: 1197-1208.

Villamil, M.; Bollero, G.; Darmody, R.; Simmons, F.; and Bullock, D. 2006. No-till corn/soybean systems including winter cover crops. *Soil Science Society of America Journal*, 70: 1936-1944.

Wigmore, J.H. 1913. The Problem of Proof. *Illinois Law Review*, 8: 77-103.

Wigmore, J. H. 1937. *The Science of Judicial Proof: As Given by Logic, Psychology, and General Experience and Illustrated in Judicial Trials, 3rd edition.* Boston, MA: Little, Brown & Co.

Wise, K., and Mueller, D. 2011. Are Fungicides No Longer Just For Fungi? An Analysis of Foliar Fungicide Use in Corn. *APSnet Features*. doi:10.1094/APSnetFeature-2011-0531.

Witten, I.; Frank, E.; and Hall, M. 2011. *Data Mining: Practical Machine Learning Tools and Techniques*. Morgan Kaufmann.

Zadeh, L. 1983. The Role of Fuzzy Logic in the Management of Uncertainty in Expert Systems. *Fuzzy Sets and Systems*, 11:199-227